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On-line PD Detection and Localisation in Cross-bonded HV Cable Systems

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ABSTRACT

This paper addresses the detection and localization of partial discharge (PD) in cross-bonded (CB) high voltage (HV) cables. A great deal has been published in recent years on PD based cable insulation condition monitoring, diagnostics and localisation in medium voltage (MV) and high voltage (HV) cables. The topic of pulse propagation and PD source localization in CB HV cable systems has yet to be significantly investigated. The main challenge to PD monitoring of CB HV cables is as a result of the interconnectedness of the sheaths of the three single phase cables. The cross-bonding of the sheaths makes it difficult to localise which of the three phases a PD signal has emanated from. Co-axial cables are used to connect cable sheaths to cable link boxes, for ease of installation and protection against moisture. A second challenge is, therefore, the coupling effect when a PD pulse propagates in HV cable joints and the co-axial cables, making PD detection and localisation more complex. The paper presents experimental investigations into PD pulse coupling between the cable centre conductor and the sheath and the behavior of PD pulse propagation in CB HV cables. It proposes a model to describe PD pulse propagation in a CB HV cable system to allow monitoring and localization, and also presents the knowledge rules required for PD localization in CB HV cable systems.

Index Terms — Cable, cross-bonding, partial discharge, on-line insulation condition monitoring, coupling effect, PD localisation.

1 INTRODUCTION

POWER cables are subject to electrical, thermal, mechanical, and environmental stresses on a constant basis when in service. These stresses, and occasionally problems resulting from inadequate installation and maintenance practices, lead to insulation degradation and/or defects [1] [2]. In many instances the deterioration leads to partial discharge (PD) which exacerbates the degradation of the insulation and shortens the cable life [3]. As detection of incipient faults through PD monitoring allows timely maintenance and replacement of assets to be carried out and unplanned outage to be reduced [4] [5] it is of great importance to industry.

Although a great deal of research on PD based cable insulation monitoring, diagnostics and localisation in medium voltage (MV) and high voltage (HV) cables has been published in recent years, the study of pulse detection and localization in cross-bonded (CB) cable systems has yet to be reported. HV cable systems are usually designed as CB systems to minimize screen losses and to limit voltage rise. In 3-phase, single core CB cable systems a whole cable circuit is normally divided into major sections each consisting of three minor sections of similar length, see Figure 1. As indicated in Figure 1, a major section of an 110 kV installation in Wuhan, at the section terminations the sheaths of the cable are cross-bonded and at the ends of the major section the sheaths are grounded [6]. The cross-bonding of the sheaths normally occurs within adjacent link-boxes and MV cables are used for connecting cable sheaths to the link-box for ease of installation and protection against moisture. A schematic diagram of a CB cable system is shown in Figure 1.
Inductive and capacitive circuit parameters are frequency dependent, where frequency is given by \( f \) (Hz). The line is described by its propagation constant \( \gamma \), with attenuation characteristic \( \alpha \) (dB/m) as real and phase characteristic \( \beta \) (rad/m) as the imaginary part. The following relation holds:

\[
\gamma(\omega) = \alpha(\omega) + j\beta(\omega) = \sqrt{(R + j\omega L)(G + j\omega C)}
\]  

(1)

Where: \( \omega = 2\pi f \) is angular velocity (rad/sec).

As different frequencies of a pulse travel along a cable, they suffer different degrees of attenuation and delay. Attenuation \( \alpha \) is due to losses in the solid dielectric and propagation through the resistance of the conductor, sheath and semi-conducting layers. Normally, attenuation severity increases with frequency. Dispersion, a phenomenon whereby signals of different frequency travel along a cable at different speeds, results in frequency-dependent phase shifts. Attenuation and dispersion will, therefore, decrease the amplitude and increase the width of the pulse. The change in pulse width results in an increase in the pulse rise time as it propagates along a cable [9].

The propagation constant of a wave travelling along a transmission line of segment length \( l \) is the complex ratio between the voltages of output (transmitted) pulse \( V_{out} \) and the input (incident) pulse \( V_{in} \) of the line segment. If a length of cable is considered as a linear system, this ratio represents the cable Transfer Function \( H_{cable}(\omega) \), as presented in equation (2):

\[
H_{cable}(\omega) = \frac{V_{out}}{V_{in}} = e^{-\alpha(\omega)2l} = e^{-(\alpha(\omega)+j\beta(\omega))2l}
\]  

(2)

Although input and output pulses cannot be measured directly, due to existence of impedance mismatches in the system, a calibration procedure has been developed to obtain \( H_{cable}(\omega) \) [10]. The set-up and procedure can be discussed using Figure 3: line 1 is a 0.5m length of 50 ohm co-axial cable connecting the pulse generator to an oscilloscope, line 2 is a 20m length of the co-axial cable connecting the pulse generator to the cable under test. Initially line 2 is short-circuited and the measured signal from this configuration is recorded as \( V_3^{\text{short}} \), thereafter the device under test (DUT) is connected to line 2 and data collected. \( V_3^{m} \) is the signal due to impedance mismatch between line 2 and DUT, \( V_3^{s} \) is the signal detected due to DUT. The cable transfer function can be obtained from:

\[
H_{cable}(\omega) = e^{-\alpha(\omega)2l} = \frac{V_{3}^{\text{short}}}{V_{3}^{m} - V_{3}^{\text{short}}}
\]  

(3)

Where \( V_3^{m} \) and \( V_3^{\text{short}} \) are as described above.
Attenuation and phase characteristics can be determined from (3) as

\[ \alpha(\omega) = -\frac{1}{2l} \ln |H_{\text{cable}}(\omega)| \]  

(4)

\[ \beta(\omega) = -\frac{1}{2l} \angle H_{\text{cable}}(\omega) \]  

(5)

Following the calibration procedure, an experiment was carried out by injecting a calibration pulse, shown in Figure 4, into a 38.8m length of 11kV single core Ethylene-Propylene-Rubber (EPR) insulated cable. The pulse generator was designed and constructed to produce signals, such as those in Figure 4, which mimicked PD signals recorded on practical cable systems. The attenuation and phase characteristics obtained from the transfer function of the EPR cable are given in Figures 5(a) and 5(b) respectively.

Results shown in Figure 5 indicate that the cable behaves like a transmission line up to a frequency of 80MHz, beyond this the characteristics becomes complicated and the cable cannot be represented using the transfer function as described previously.

2.2 THE COUPLING EFFECT OF PULSE PROPAGATION

To investigate the coupling effect when a pulse propagates in HV cable joints and CB link-lines (MV cable), a series of different test arrangements were developed. In all cases, 50Ω signal coaxial cables were used in the laboratory investigation due to unavailability of real-world cables of reasonable lengths. Due to the similarity in cable construction, the pulse coupling principle in coaxial cable and power cable are the same.

The initial test set-up, as shown in Figure 6(a), was constructed to investigate the relationship between the detected pulse from HFCTs clipped around the CB link-line and the detected pulses travelling along the centre conductor and sheath of cable.

Figure 6(b) shows that when two pulses individually propagate along the conductor and sheath of a coaxial cable, the measured pulse detected by a CT clipped around the cable is the resultant sum of the two pulses.
In order to confirm the polarity and propagation direction of the coupling pulses, which allowed the calculation in equation 6 to be completed, two further experiments were completed. These are the same as those described in Figure 7 except that the HFCT on the 15m copper wire was 9.9m away from End A of the cable. Figure 10 demonstrates that current pulse I₂, from the HFCT on the 15m copper wire, is delayed by 33ns when compared with the other two pulses, i.e. the expected pulse propagation time through 9.9m of copper wire (9.9m/3*10^8m/s=33ns).

It can, therefore, be concluded that when a positive pulse I₁ propagates into one end of a cable sheath, a coupling event causes charge to be developed in the center conductor. From this charge, two pulses are generated which propagate in opposite directions in the cable center conductor (in Figure 11a). The two coupled pulses (I₁’ and I₂) have the same shape, same amplitude but, unexpectedly, opposite polarities. This statement is justified as follows: to obtain the current pulse magnitudes in Figures 11(a) and 11(b) the current in the coaxial cable, I₃, was obtained by subtracting I₁ from I₁’; this indicates that the current, I₃, must come from a positive current pulse, I₁, and a negative current pulse I₂, as shown in Figures 11(a) and 11(b). A similar argument can be used for an injected pulse of the opposite polarity.

The coupling efficiency where the pulse is injected into the sheath, set-up 1, is defined as kₛ (kₛ=|I₁’/I₁|). Similarly the coupling efficiency in set-up 2, where the pulse is injected into the center conductor, is defined as kₖ (kₖ=|I₁’/I₁|). It is noted that the value of kₖ is a little greater than kₛ.
3 PULSE PROPAGATION IN CB HV CABLE SYSTEMS

3.1 PD MONITORING IN HV CB CABLE SYSTEM

PD sensors can be installed at the major intersections or terminations of a CB HV cable system. For an example system, as shown in Figure 12, there are four possible sites, numbered 1 to 4. To obtain a low-cost solution, the optimal method for installation of PD sensors to monitor and localize PD pulses would be to install 6 sensors in the two sets of joints at ② and ③.

Figure 12. Proposed sensor installation for on-line PD monitoring in a CB HV cable system

3.2 PULSE PROPAGATION IN HV CB CABLE SYSTEM

The parameters of a CB cable system are dependent on the physical size of HV cables and CB link-lines, earth resistance, etc. A model has been developed to analyze PD propagation in a CB HV cable system according to a practical system in Wuhan, China, see Figure 13. The cable model has two CB link-boxes; each connects three CB link-lines (MV cables). The sheath of Phase A section 1 connects through the center conductor of a CB link-line to link-box 1, at link-box 1 the sheath of Phase B section 2 is connected to it via the sheath of a CB link-line. Similar connectivity can be shown for the other Phase sheaths.

Figure 13. Model of a Wuhan CB HV cable system

Using the model a study has been undertaken to investigate the effect of PD signals emanating from four sites of origin. Three of the sites for PD pulses are the three sections of phase A, the fourth is taken as being in joint A1. Following the earlier discussion, the PD pulses at the site of origin are all assumed to produce positive pulses travelling in opposite direction along the center conductor, \( I_1 \) in Figure 14, while negative pulses travel in opposite direction along the HV cable sheath, \(-I_1\) in Figure 14. The characteristics obtained in the preceding section of the paper are applied to analyze the pulse propagation in CB cable systems.

3.2.1 PD from section 1 of phase A

The first case is a PD source in section 1 of phase A, assumed to be \( I_1 \) metres away from joint A1, as shown in Figure 14. Components of the original PD pulses, \( \pm I_1 \), propagate along the cable to joint A1 (Figure 14), CB link-lines and CB link-box (Figure 15). The resultant pulses are detected by HFCTs at phase A, B, C of the CB link-lines. Equations relating to pulse propagation are given in (8)-(13):

\[
\begin{align*}
I_2 &= I_1 e^{-\gamma_1 t} \\
I_3 &= k_{mc} I_2 \\
I_4 &= -k_{mc} I_2 \\
I_5 &= k_{ms} I_3 \\
I_6 &= I_3 \cdot I_4 \\
I_7 &= -I_5 - I_2 \\
\end{align*}
\]

Where \( I_1 \) is the component of the original PD current pulse at the source, \( \gamma_1 \) is the propagation constant of the HV cables, \( k_{mc} \) is the coupling coefficient of HV cables, \( k_{mc} \) and \( k_{ms} \) are the coupling coefficient of CB link-lines (MV cables).

Figure 14. Coupling effect of a PD pulse propagating through a cable joint

The equations relating to propagation in the CG links, Figure 15, are given in equations (14)-(19):  

\[
\begin{align*}
I_8 &= I_7 e^{-\gamma_2 t/2} \\
I_9 &= I_6 e^{-\gamma_2 t/2} \\
I_{10} &= -k_{ms} I_8 + k_{mc} I_9 \\
I_{11} &= I_8 - k_{mc} I_9 \\
I_{12} &= -k_{ms}^2 I_8 + I_9 \\
I_{13} &= k_{ms}^2 I_8 - k_{mc} I_9 \\
\end{align*}
\]
Where $\gamma_2$ is the propagation constant of the CB link-lines and $l_2$ is the length of the CB link-line which connects to joint A1.

\[ I_{HFCT1A} = I_8 + I_9 \quad (20) \]
\[ I_{HFCT1B} = -I_{10} - I_{11} \quad (21) \]
\[ I_{HFCT1C} = -I_{12} - I_{13} \quad (22) \]

Using equation (8)-(19), it can be shown that

\[ I_{HFCT1A} = (k_{hc} + k_{mc} - k_{ns}k_{hc} - 1)I_1e^{-\gamma_1l_1}e^{-\gamma_2l_2} \quad (23) \]
\[ I_{HFCT1B} = [(1-k_{ns})(k_{mc}k_{hc} + 1) + (k_{mc} - k_{ns})(k_{hc} + k_{mc})]I_1e^{-\gamma_1l_1}e^{-\gamma_2l_2} \quad (24) \]
\[ I_{HFCT1C} = [(k_{ns} - k_{ns}^2)(k_{ns}k_{hc} + 1) + (k_{mc} - 1)(k_{hc} + k_{mc})]I_1e^{-\gamma_1l_1}e^{-\gamma_2l_2} \quad (25) \]

For simplicity it is assumed that $k_{mc}=k_{hc}=k_c$, $k_{ns}=k_s$, using values obtained from Section 2.2, then

\[ I_{HFCT1A}:I_{HFCT1B}:I_{HFCT1C} = -0.378:0.567:-0.215 \quad (26) \]

The relationship between the magnitudes and polarities of three pulses detected by HFCTs close to CB link-box 1 is shown in Figure 16. This indicates that, as a result of an initial PD pulse in Phase A, the signal detected in phase B has largest magnitude pulses (almost twice that in Phases A and C). The PD pulse in Phase B has positive polarity, while pulses detected in phase A and C both have a negative polarity.

3.2.2 PD from section 2 of phase A

Using the principle shown above, the propagation of PD from section 2 of phase A is studied. The results of the pulses detected by HFCTs close to CB link box 1 and CB link box 2 are given in equation (27)-(28) and Figures 17 and 18.

In Figure 17, at CB link-box 1, the signal detected in Phase C has the largest magnitude, Phase A (where the pulse originated) is lower and B is lowest. Phase C has positive polarity, pulses detected in both phase A and B are negative polarity. Comparison of the data relating to a PD in section A1, Section 3.2.1 and equation (26) and Figure 16, with that of equation (28) and Figure 18 demonstrates that the three pulses at CB link-box 2 are the same.

\[ I_{HFCT1A}:I_{HFCT1B}:I_{HFCT1C} = -0.424:-0.204:0.552 \quad (27) \]
\[ I_{HFCT2A}:I_{HFCT2B}:I_{HFCT2C} = -0.378:0.567:-0.215 \quad (28) \]
3.2.3 PD from section 3 of phase A

Applying the similar procedure to develop the effect of PD from section 3 of phase A, the results of the pulses detected by HFCTs close to CB link box 2 are given in equation (29) and Figure 19.

From Figure 19 and equation (29) it can be seen that the three pulses at CB link-box 2 are the same as those at CB link-box 1 in section 3.2.2.

\[ I_{HFCT2A} - I_{HFCT2B} - I_{HFCT2C} = -0.424 : -0.204 : 0.552 \quad (29) \]

3.2.4 PD in joint A1

Applying the similar procedure to develop the effect of PD from joint A1, and the results of the pulses detected by HFCTs close to CB link box 1 are given in equation (30) and Figure 20.

From Figure 20, the signal detected in phase A at CB link-box 1 has the opposite polarity to that of the other phases, and the amplitude is about twice that of the others.

\[ I_{HFCT2A} - I_{HFCT2B} - I_{HFCT2C} = -1.283 : 0.579 : 0.539 \quad (30) \]

4 KNOWLEDGE RULES FOR PD LOCALISATION IN CROSS-BONDED CABLE SYSTEMS

According to the simulation results of pulse propagation in CB HV cable systems in Section 3, PD sources emanating from different locations manifest different characteristics of pulse magnitude and polarity when detected by the HFCTs installed at CB link-lines close to the two CB link-boxes. This knowledge can be used for PD monitoring and localization in CB cable systems. The procedure can be used to determine the optimal method for PD sensor installation in other, more complex systems. PD localization in HV CB cable systems includes two steps.

The first step is to obtain knowledge rules to determine from which phase and section of the CB cable system a PD source emanated from. Using the Wuhan CB system as an example, the knowledge rules given in Table 1 indicate that different PD sources have unique relationships with the polarity and magnitude of the pulses detected by the 6 HFCTs in a major cable section.

<table>
<thead>
<tr>
<th>PD source in</th>
<th>HFCTs at CB link-box 1</th>
<th>HFCTs at CB link-box 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>B</td>
<td>C</td>
</tr>
<tr>
<td>Section A1</td>
<td>-2</td>
<td>+1</td>
</tr>
<tr>
<td>Section A2</td>
<td>-2</td>
<td>-3</td>
</tr>
<tr>
<td>Section A3</td>
<td>-2</td>
<td>-3</td>
</tr>
<tr>
<td>Section B1</td>
<td>-3</td>
<td>-2</td>
</tr>
<tr>
<td>Section B2</td>
<td>+1</td>
<td>-2</td>
</tr>
<tr>
<td>Section B3</td>
<td>+1</td>
<td>-2</td>
</tr>
<tr>
<td>Section C1</td>
<td>+1</td>
<td>-3</td>
</tr>
<tr>
<td>Section C2</td>
<td>-3</td>
<td>+1</td>
</tr>
<tr>
<td>Section C3</td>
<td>-3</td>
<td>+1</td>
</tr>
<tr>
<td>Joint A1</td>
<td>-1</td>
<td>+2</td>
</tr>
<tr>
<td>Joint A2</td>
<td>+2</td>
<td>-1</td>
</tr>
<tr>
<td>Joint B1</td>
<td>+2</td>
<td>+2</td>
</tr>
<tr>
<td>Joint B2</td>
<td>+2</td>
<td>+2</td>
</tr>
<tr>
<td>Joint C1</td>
<td>+2</td>
<td>+2</td>
</tr>
<tr>
<td>Joint C2</td>
<td>+2</td>
<td>+2</td>
</tr>
</tbody>
</table>

Where “+” and “-” represents positive and negative polarity respectively; numbers of “1, 2, 3” represent the relative level of PD pulse magnitude, “1” is the greatest, “2” is the middle and “3” the smallest.
This Table presumes that the PD pulses at the site of origin are positive pulses travelling along the center conductor of the cable while negative pulses travel along HV cable sheath. If the PD pulses at the site of origin are assumed to be negative pulses travelling in the center conductor and positive pulses in the cable sheath, only the polarity of the results above will reverse, the magnitude relationships will remain the same.

The second step is to determine the distance between the PD source and the position where a HFCT is installed. This can be carried out using the Rise Time Transfer Function (RTTF) method for PD localization in a single phase cable.

5 CONCLUSION

Online PD monitoring in CB HV cable systems is usually carried out through HFCTs being installed at cable joints or terminations where HFCTs can be clipped around CB link-lines. Due to the interconnectedness of sheaths of the three phases, PD pulses detected by a HFCT comprise signals from the sheaths of three phases. The complex coupling effects, when pulses propagate in HV cable joints and CB link-lines, make it difficult to localize which of the three phases a PD signal has emanated from. This paper studied the propagation characteristics, pulse attenuation and coupling effects of pulses propagating in cables by laboratory experiments.

A model, based on a practical CB cable system, has been developed to analyze PD pulse propagation in a CB cable system. The study applies the propagation characteristics gained from the laboratory work to demonstrate how understanding of signal propagation in CB system can be used to identify sites of origin of PD. Based on the study, the optimal method for PD sensor installation to monitor and localize PD pulses in CB systems is proposed, i.e. to install HFCT sensors round the CB link-lines close to the CB link-boxes. In addition, knowledge rules to locate the phase and section of a PD source in CB cable systems are obtained as different PD source locations have unique relationships with the polarities and magnitudes of the pulses detected by HFCTs.

REFERENCES


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